







Further Development and Testing of M₁ - M₂ as a Depth Discriminant at Local Distances

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A signal-to-noise ratio of 2 is for well-constrained necessarv measurements



Figure 6: (Top Left) Comparison of automatic (AUTO) and manual (MAN) duration measurements (Lower Right) The difference in AUTO vs MAN M, calculations as a function of SNR (Lower Left) A (Lower Left) The difference in AUTO vs MAN M_c calculations as a function of CC (Lower Right) A comparison of AUTO and MAN M, calculations using a SNR threshold taken from the top right. comparison of AUTO and MAN M_c calculations using a CC threshold taken from the bottom left.





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- have (red bars) and don't have (black stair outline) refined locations and/or magnitudes.

7. Summary

* The M₁-M_c depth discriminant is portable

*Automatic amplitude and duration measurements correlate with manually determined measurements

* Velocity heterogeneities are likely the cause of longer duration for shallow events

Koper, K.D., Pechmann, J.C., Burlacu, R., Pankow, K.L., Stein, J., Hale, J.M., Roberson, P. and McCarter, M.K., (2016), Magnitude-based discrimination of man-made seismic events from naturally occurring earthquakes in Utah, USA. Geophysical Research Letters, 43(20). -Pechmann, J.C., Nava, S.J., Terra, F.M. and Bernier, J.C., (2007), Local magnitude determinations for Intermountain Seismic Belt earthquakes from broadband digital data. Bulletin of the Seismological Society of America, 97(2), pp.557-574. -Wessel, P. and Smith, W.H., (2016), The Generic Mapping Tools, GMT, Version 4.5. 15: Technical Reference and Cookbook. School of Ocean and Earth Science and Fechnology, University of Hawaii at Manoa. Petersson, N.A.; Sjögreen, B. (2014), SW4 v1.1 [software], Computational Infrastructure for Geodynamics, doi: 10.5281/zenodo.571844, url: https://geodynamics.org/cig/software/sw4/